Forecasting Brazilian Exchange Rates with Nonlinear Models

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Abstract

This work investigates the hypothesis that the nonlinear models of multilayer perceptron and radial basis function neural networks and the Takagi-Sugeno (TS) fuzzy system are able to provide a more accurate out-of-sample forecast than the traditional ARMA and ARMA-GARCH linear models. Using series of Brazilian exchange rate (R$/US$) returns with 15 min., 60 min., 120 min., daily and weekly basis, the one-step-ahead forecast performance is compared. Results indicate that forecast performance is strongly related to the series’ frequency and the forecasting evaluation shows that nonlinear models perform better than their linear counterparts. In the trade strategy based on forecasts, nonlinear models achieve higher returns when compared to a buy-and-hold strategy and to the linear models.

1. Introduction

The literature related to financial time series has registered since the 1990’s important advances with the incorporation of newly developed methods that attempt to determine patterns of relationships in financial market data. These approaches are, in general, computationally intensive and characterized by the capacity of modeling nonlinear dynamic systems, i.e., systems in which the variables of the environment possess complex patterns of interrelationships that alter throughout time.

Given the growing report of presence of nonlinear structures in financial time series, the use of deterministic linear models to describe and forecast financial prices movements has been criticized. The existence of multiples regimes in economic and financial time series, like expansions and recessions or high and low volatility, suggests that nonlinear models are more appropriate, due to their grater ability of capture nonlinear features [1,2]. This aspect has stimulated researchers of diverse academic backgrounds to apply modern techniques of system identification to various problems in Economics and Finance, like asset pricing [3], investment selection [4], game theory [5] and, principally, time series forecasting [6,7].

Two relevant approaches, among many others, used for forecasting financial series are fuzzy systems and neural networks. In recent years, researchers have proposed a varied spectrum of methodologies for identification and nonlinear forecasting based upon fuzzy systems to deal with nonlinear systems. On the other hand, neural networks have received attention in the last decade due to their abilities to perform learning, thus applied in a great number of situations. This article is organized as follows. The next section describes the linear and nonlinear models. In section 3 and 4 we present the methodology of the study and the results, respectively. And finally, in section 5, we bring concluding remarks.

2. Forecast models

2.1 Linear models

Following the Box-Jenkins methodology, an autoregressive moving average process ARMA\((p,q)\) can be written as

\[ y_t = \phi_0 + \phi_1 y_{t-1} + \ldots + \phi_p y_{t-p} + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \ldots + \theta_q \varepsilon_{t-q} \]  

(1)
where \( \{e_t\} \) is a white noise process with zero mean and a constant variance of \( \sigma^2 \). The terms \( \phi_p, \phi_{p-1}, \ldots, \phi_0 \) and \( \theta_q, \theta_{q-1}, \ldots, \theta_0 \) are parameters that must be estimated. Also considering the stylized fact of non-constant residual variance, we use ARMA models with an autoregressive conditional heteroskedasticity process – ARMA(p,q)-GARCH(p,q) models [9]. From the equation 1, we consider the generator process of \( \{e_t\} \) as given by

\[
\begin{align*}
    e_t &= v_t \sqrt{h_t}, \quad v_t \sim \text{IID}(0,1) \quad (2) \\
    h_t &= \alpha_0 + \sum_{i=1}^{q} \alpha_i e_{t-i}^2 + \sum_{i=1}^{p} \beta_i h_{t-i}. \quad (3)
\end{align*}
\]

### 2.2 Nonlinear Models

The output of a single layer perceptron neural network model (NN-MLP) with \( h_1 \) hidden units (and a linear component) can be defined as

\[
y_{t+h}^h = w_0^h Z_t + \sum_{i=1}^{n} w_{i}^h g(Z_t) + \varepsilon_{t+h} \quad (4)
\]

where \( g(x) = 1/(1+e^{-x}) \) and \( Z_t = (1, y_t, y_{t-1}, \ldots, y_{t-p}) \). The Levenberg-Marquardt (LM) algorithm [10] was used for training the network. The update process of the LM algorithm can be expressed as

\[
w_{t+1} = w_t - (J^T J + \lambda I)^{-1} J^T r \quad (5)
\]

where \( w_{t+1} \) and \( w_t \) are the weights in time \( t+1 \) and \( t \), respectively, \( r \) is the residual function, \( J \) is the Jacobian matrix defined as \( J = \frac{\partial r}{\partial w} \) and \( \lambda \) is a scalar that defines the velocity of the training process.

The nonlinear approximation of a radial basis function (NN-RBF) neural network with \( m \) hidden units is specified by

\[
y_{t+h}^h = \sum_{i=0}^{m} w_i \varphi(\|Z_t - \mu_i\|) + \varepsilon_{t+h} \quad (6)
\]

where \( \varphi(\cdot) \) is the basis function and \( \mu_i \) is the centre of the \( i \)-th basis function. \( \varphi(\cdot) \) is usually defined as a Gaussian function \( \varphi(x) = \exp(-x^2/2\sigma^2) \), where \( \sigma \) define the width of each function. The least squares solution of the weights \( w_i \) satisfies \( (A^T A)w = A^T b \) where \( A \) is the matrix with element \( A_{ij} \) representing the output element of the \( j \)-th hidden neuron for the \( i \)-th input.

The fuzzy system tested was a TS type with Gustafson-Kessel [11,12] fuzzy covariance matrix clustering (rule preceding) and least squares (rule consequent). The IF-THEN rules of this model assume the general form

\[
R_i : \text{IF} \quad x_i \text{IS} A_{i1} \text{AND} \ldots \text{AND} \quad x_n \text{IS} A_{in} \quad \text{THEN} \quad \hat{y}_i = a_i x + b_i, \quad i = 1, 2, \ldots, K \quad (7)
\]

where the preceding IF defines the preceding portion (premise) while the rule functions THEN constitute the consequent part of the fuzzy system; \( R_i \) is the \( i \)-th rule, \( x = [x_1, \ldots, x_n]^T \) is the vector of the rule input variables (preceding), and \( y_i \) is the output of the rule. The aggregate output \( \hat{y} \) of the model is it the weighted mean of the rule’s consequent,

\[
\hat{y} = \sum_{i=1}^{K} \beta_i(x)(a_i x + b_i),
\]

where \( \beta_i(x) = \prod_{j=1}^{n} \mu_{A_{ij}}(x_j) \) it is the level of activation of the \( i \)-th rule, \( \mu_{A_{ij}}(x_j) : \mathbb{R} \rightarrow [0,1] \) it is a Gaussian-type membership function associated to each fuzzy set \( A_{ij} \), described by

\[
\mu_{A_{ij}}(x_j) = \exp\left[-\frac{1}{2} \left(\frac{x_j - m_{ij}}{\sigma_{ij}}\right)^2\right] \quad (9)
\]

where \( m_{ij} \) and \( \sigma_{ij} \) are the center and the width of the membership function, respectively.

### 3. Methodology

In this work, series of 15min., 60 min. and 120 min. returns (first difference of log-prices) from 01/01/2002 to 01/01/2003 and daily and weekly returns (first difference of log-prices) from 01/01/2000 to 01/01/2004 of the Brazilian exchange rate (R$/US$) were used. The first 80% of the data were used for model estimation while the last 20% were used for validation and one-step-ahead out-of-sample forecasting. Table 1 shows the number of observations for estimation and validation (forecasting) steps for each series.

In table 2, the results of the specification tests Augmented-Dickey-Fuller (ADF) unit root test, the ARCH LM test and the BDS test for nonlinearity are shown. Results indicate that all series are stationary and contain ARCH effects. Departing from residuals of a AR(1)-GARCH(1,1) model, the BDS test indicates the presence of nonlinearity in all series. The results show
that the higher the series' frequency, the higher the level of nonlinearity.

<table>
<thead>
<tr>
<th></th>
<th>15 m.</th>
<th>60 m.</th>
<th>120 m.</th>
<th>Daily</th>
<th>Weekly</th>
</tr>
</thead>
<tbody>
<tr>
<td>Estimation</td>
<td>4,515</td>
<td>1,180</td>
<td>730</td>
<td>804</td>
<td>180</td>
</tr>
<tr>
<td>Validation</td>
<td>1,128</td>
<td>294</td>
<td>183</td>
<td>201</td>
<td>20</td>
</tr>
<tr>
<td>Total</td>
<td>5,643</td>
<td>1,474</td>
<td>913</td>
<td>1,005</td>
<td>200</td>
</tr>
</tbody>
</table>

Table 1. Number of observations for estimation and validation steps.

<table>
<thead>
<tr>
<th>Series</th>
<th>15 m.</th>
<th>60 m.</th>
<th>120 m.</th>
<th>Daily</th>
<th>Weekly</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADF</td>
<td>-13.61*</td>
<td>-7.30*</td>
<td>-7.69*</td>
<td>-14.88*</td>
<td>-13.80*</td>
</tr>
<tr>
<td>ARCH</td>
<td>58.57*</td>
<td>23.57*</td>
<td>9.75*</td>
<td>174.9*</td>
<td>25.17*</td>
</tr>
<tr>
<td>LM</td>
<td>0.025</td>
<td>0.032</td>
<td>0.034</td>
<td>0.036</td>
<td>0.032</td>
</tr>
<tr>
<td>BDS</td>
<td>16.64*</td>
<td>11.51*</td>
<td>9.57*</td>
<td>11.98*</td>
<td>4.29*</td>
</tr>
</tbody>
</table>

Table 2. Specification tests results. * indicates statistic significance at 95% confidence level.

In the neural network models, we used a single hidden layer network for the perceptron and radial basis function networks. The number of neurons that produce smaller forecast error were defined through various simulations. In the TS fuzzy system, the number of membership functions that produce best results were also defined through simulations.

The NARX and NARMAX (Nonlinear Auto-Regressive Moving Average with eXogenous inputs) approaches were used for the nonlinear dynamic representation of the series [13]. A NARX structure can be defined as

\[ y(t) = f \left( \sum_{i=1}^{n_y} b_{yi} y(t-i) + \sum_{i=1}^{n_u} b_{ui} u(t-i) \right) + e(t) \]  \hspace{1cm} (10)

and the NARMAX structure can be defined as

\[ y(t) = f \left( \sum_{i=1}^{n_y} b_{yi} y(t-i) + \sum_{i=1}^{n_u} b_{ui} u(t-i) + \sum_{i=1}^{n_e} b_{ei} e(t-i) \right) + e(t) \]  \hspace{1cm} (11)

where \( y(t), u(t) \) and \( e(t) \) are the system output, the exogenous inputs and the moving average component, respectively; \( n_y, n_u \) and \( n_e \) are the maximum lags of the outputs, the inputs and the moving average, respectively. \( f \) is a nonlinear function that describes the dynamics of the system.

The Akaike Information Criterion was used for choosing the number of terms and its lags in the linear and nonlinear models. In the results, only the best-fit model structure is presented.

The forecast was evaluated using the following criteria:

- Root mean squared error (RMSE):

\[ RMSE = \sqrt{\frac{1}{m} \sum_{j=1}^{m} e_{t+j}^2} \]  \hspace{1cm} (12)

where \( e \) is the forecast error for the \( t+j \) observation and \( m \) is the number of observations;

- U-Theil inequality index:

\[ U - \text{Theil} = \sqrt{\frac{\sum_{t=T+1}^{T+m} (\hat{y}_t - y_t)^2}{\sum_{t=T+1}^{T+m} (\hat{y}_t)^2/m}} \]  \hspace{1cm} (13)

where \( \hat{y}_t \) is the estimated (forecasted) value for the period \( t \), \( y_t \) is the observed (real) value and \( m \) is the number of observations;

- Percentage of corrected predicted signals (CPS);

- Pesaran-Timmermann (PT) predictive failure statistic [14], defined by

\[ PT = \sqrt{\frac{\sum_{t=T+1}^{T+m} (\hat{P} - \hat{P}_s)^2}{\sum_{t=T+1}^{T+m} (\hat{P}_s)^2/m}} - N(0,1) \]  \hspace{1cm} (14)

where \( \hat{P} \) is the percentage of corrected predicted signals, \( \hat{P}_s \) is the expected value of \( \hat{P} \), given by \( \hat{P}_s = P \hat{P}_s + (1 - P)(1 - \hat{P}_s) \), where \( P \) is the percentage of negative signals and \( P_s \) is the percentage of positive signals. \( \text{var}(\hat{P}) \) and \( \text{var}(\hat{P}_s) \) are given by

\[ \text{var}(\hat{P}) = n^{-1}\hat{P}(1 - \hat{P}) \]

\[ \text{var}(\hat{P}_s) = n^{-1}(2\hat{P} - 1)^2\hat{P}_s(1 - \hat{P}_s) + n^{-1}(2\hat{P}_s - 1)^2\hat{P}_s(1 - \hat{P}_s) \]

4. Results

Tables 3 to 7 show the forecast evaluation for the financial series used in this work. The most important result is that nonlinear models performed better than linear models in all series. In the series of 15 min. returns, the best linear model obtained a U-Theil index of 0.867 and predicted correctly 44% of the returns movements (signals direction), although without statistic significance. On the other hand, the best nonlinear model obtained a U-Theil index of 0.786 and predicted correctly 54% of the returns movements, with a 99% statistic significance level, measured by the PT statistic.

In the series of 60 min. returns, all linear models returned U-Theil indexes over 0.8 and none of them achieved statistic significance in the forecasts. The best nonlinear model, however, returned a U-Theil index of 0.640 and predicted successfully 60% of the signals direction. All nonlinear models achieved statistic significance in the forecasts.
Table 3. Forecast results for the Brazilian 15 min. exchange rate returns. * indicates that PT statistic is significant at 95% confidence level.

Table 4. Forecast results for the Brazilian 60 min. exchange rate returns. * indicates that PT statistic is significant at 95% confidence level.

Table 5. Forecast results for the Brazilian 120 min. exchange rate returns. * indicates that PT statistic is significant at 95% confidence level.

Table 6. Forecast results for the Brazilian daily exchange rate returns. * indicates that PT statistic is significant at 95% confidence level.

Table 7. Forecast results for the Brazilian weekly exchange rate returns. * indicates that PT statistic is significant at 95% confidence level.

Table 5 shows the forecast results for the Brazilian 120 min. exchange rate returns. The nonlinear models returned smaller U-Theil indexes (with exception of the TS model) and higher percentage of corrected predicted signals. This result is also verified in the series of daily returns (Table 6). The NN-MLP-NARX forecasted correctly 61% of the daily exchange rate movements, while the ARMA-GARCH model forecasted correctly 54%.

In the series of Brazilian weekly exchange rate returns (Table 7), the NN-MLP-NARMAX model obtained a U-Theil index of 0.469 and predicted correctly 82% of the signals direction with 99% of statistic significance, while the best linear model obtained a U-Theil index of 0.654 and predicted correctly 67% of the movements, with 95% of statistic significance.
It should be emphasized that the forecast evaluation based on the size of the forecast error (RMSE) was not useful, in some cases, to distinguish between the best and the worst models. In the case of the 15 min. and weekly returns, the RMSE of the nonlinear models was equal or even greater than the RMSE of the linear models.

It is also clear that the lower is the series’ frequency, the greater is the model’s ability for making good forecasts. Tables 3 to 7 show that when the frequency is decreasing, the quality of the forecast increases. A possible explanation is that high frequency time series exhibits a greater level of nonlinearity, i.e. a more complex data generator process, what makes the forecast a difficult task (see Table 2). In this sense, the worst forecast results were obtained for the 15 min. returns (table 3) and the best results for the weekly returns series (table 7).

Table 8 summarizes the forecast results of the best performance model for each series. The NN-MLP model generated the best forecasts for all of the analyzed series. The NARMAX structure was the best mathematical representation, with exception in the daily returns series. U-Theil indexes decreased from 0.786 in the series of 15 min. to 0.469 in the series of weekly returns, while the percentage of corrected predicted signals rose from 54% to 82%. This results show that nonlinear models performed better than linear models, and the quality of the forecast are closely related to the series’ frequency.

<table>
<thead>
<tr>
<th>Series</th>
<th>15 m.</th>
<th>60 m.</th>
<th>120 m.</th>
<th>Daily</th>
<th>Weekly</th>
</tr>
</thead>
<tbody>
<tr>
<td>Best model</td>
<td>NN-MLP</td>
<td>NN-MLP</td>
<td>NN-MLP</td>
<td>NN-MLP</td>
<td>NN-MLP</td>
</tr>
<tr>
<td>RMSE</td>
<td>0.005</td>
<td>0.001</td>
<td>0.01</td>
<td>0.001</td>
<td>0.02</td>
</tr>
<tr>
<td>U-Theil</td>
<td>0.786</td>
<td>0.640</td>
<td>0.617</td>
<td>0.700</td>
<td>0.469</td>
</tr>
<tr>
<td>CPS</td>
<td>54%</td>
<td>60%</td>
<td>61%</td>
<td>61%</td>
<td>82%</td>
</tr>
<tr>
<td>PT</td>
<td>3.62*</td>
<td>3.31*</td>
<td>3.19*</td>
<td>3.85*</td>
<td>4.32*</td>
</tr>
</tbody>
</table>

Table 8. Summary of forecast results for the best performance models. * indicates that PT statistic is significant at 95% confidence level.

Table 9 shows the results of the trade strategy based on the model’s forecast. It compares the total return, standard deviation and Sharpe index of the strategy based on the best linear model, best nonlinear model and the buy-and-hold strategy, respectively. It is assumed no transaction costs and the possibility of uncovered short. The rules of the trade strategy can be resumed as:

- Rule 1: Buy, if the forecasted value for the next period is positive;
- Rule 2: Sell, if the forecasted value for the next period is negative.

<table>
<thead>
<tr>
<th>Strategy / Model</th>
<th>Return</th>
<th>Std. Dev.</th>
<th>Sharpe</th>
</tr>
</thead>
<tbody>
<tr>
<td>AR</td>
<td>12.5%</td>
<td>3.9%</td>
<td>3.20</td>
</tr>
<tr>
<td>ARMA</td>
<td>36.5%</td>
<td>8.6%</td>
<td>4.21</td>
</tr>
<tr>
<td>MA</td>
<td>25.1%</td>
<td>6.2%</td>
<td>4.03</td>
</tr>
</tbody>
</table>

60 min.

<table>
<thead>
<tr>
<th>Strategy / Model</th>
<th>Return</th>
<th>Std. Dev.</th>
<th>Sharpe</th>
</tr>
</thead>
<tbody>
<tr>
<td>NN-MLP-NARMAX</td>
<td>48.1%</td>
<td>11.6%</td>
<td>4.13</td>
</tr>
<tr>
<td>NARMA</td>
<td>92.7%</td>
<td>28.2%</td>
<td>3.28</td>
</tr>
<tr>
<td>SN-TS-NARX</td>
<td>49%</td>
<td>12.1%</td>
<td>4.03</td>
</tr>
<tr>
<td>Buy-and-hold</td>
<td>13.6%</td>
<td>5.2%</td>
<td>2.60</td>
</tr>
</tbody>
</table>

120 min.

<table>
<thead>
<tr>
<th>Strategy / Model</th>
<th>Return</th>
<th>Std. Dev.</th>
<th>Sharpe</th>
</tr>
</thead>
<tbody>
<tr>
<td>NN-MLP</td>
<td>0.02</td>
<td>0.02</td>
<td>0.02</td>
</tr>
<tr>
<td>AR</td>
<td>36.9%</td>
<td>10.2%</td>
<td>3.40</td>
</tr>
<tr>
<td>RN-RBF-NARX</td>
<td>-18.1%</td>
<td>-4.2%</td>
<td>-4.27</td>
</tr>
<tr>
<td>Buy-and-hold</td>
<td>12.4%</td>
<td>4.8%</td>
<td>2.54</td>
</tr>
</tbody>
</table>

Daily

<table>
<thead>
<tr>
<th>Strategy / Model</th>
<th>Return</th>
<th>Std. Dev.</th>
<th>Sharpe</th>
</tr>
</thead>
<tbody>
<tr>
<td>ARMA-GARCH</td>
<td>6.3%</td>
<td>3.2%</td>
<td>2.00</td>
</tr>
<tr>
<td>NN-MLP-NARMAX</td>
<td>55.2%</td>
<td>17.2%</td>
<td>3.20</td>
</tr>
<tr>
<td>Buy-and-hold</td>
<td>-6.2%</td>
<td>1.4%</td>
<td>-4.44</td>
</tr>
</tbody>
</table>

Weekly

The trade strategy based on nonlinear models achieved greater returns in all cases when compared to the others strategies. Sharpe indexes were also higher for the strategies based on nonlinear models, demonstrating a better risk-return relation. In all analyzed series, there was a nonlinear model with higher return and Sharpe index than others strategies.

5. Conclusions

In this work, the one-step-ahead forecast performance of the nonlinear models of NN-MLP, NN-RBF and the TS fuzzy system is compared to the traditional ARMA and ARMA-GARCH linear models. The empirical evidence showed that nonlinear models performed better than linear models in forecasting Brazilian exchange rates returns with 15 min., 60 min., 120 min., daily and weekly basis. In all series, the nonlinear models achieved smaller U-Theil indexes and a higher percentage of corrected predicted signals. Forecasts were statistically significant in, at least, one nonlinear model in each series, measured by the Pesaran-Timmermann predictive failure statistic.

We also find that the accuracy of the forecasts is closely related to the series’ frequency: the less the series’ frequency, the higher the forecast accuracy. In
this sense, the best forecast results were found for the weekly returns series. A possible explanation for this result can be related to the presence of nonlinearity in the series. Nonlinearity means a more complex data generator process, or, in other words, a series less forecastable. We verify that lower frequency series exhibits a smaller level of nonlinearity. In the trade strategy, nonlinear models achieved a better risk-return relation than other strategies.

6. References